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# ***Object connectivity and full abstraction for class-based, multithreaded OO***

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- full-abstraction
- class-based calculus
- issues for full abstraction
- completeness and legal traces
- conclusion

# ***Full abstraction: starting point***

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- basically: **comparison** between 2 **semantics**, resp. 2 implied notions of **equality**
- given a **reference** semantics, the 2nd one is
  - neither too abstract = **sound**
  - nor too concrete = **complete**
- Milner [10], Plotkin [13] for  $\lambda$ -calculus/LCF
- various *variations* of the theme

# Full abstraction: standard setup

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- *reference semantics*:
  - must be natural
  - easy to define
  - non-compositional

⇒

contextual, observational

- **context**  $\mathcal{C}[\_]$  = “program with a hole”
- filling the hole with a **part** of a program (component  $C$ ): complete program  $\mathcal{C}[C]$
- what is a **context/component**?: depends on the language/syntax (sequential/parallel/functional ... contexts)

## ***F-A: standard setup (cont'd)***

- given a **closed** program  $P$ :  $\mathcal{O}(P)$  = observations  
 $\Rightarrow$  **observational equivalence**:

$$C_1 \equiv_{obs} C_2 \quad \text{iff} \quad \forall \mathcal{C}. \mathcal{O}(\mathcal{C}[C_1]) = \mathcal{O}(\mathcal{C}[C_2])$$

- given a **denotational** semantics  $\llbracket \_ \rrbracket_{\mathcal{D}}$ , resp. the implied equality  $\equiv_{\mathcal{D}}$   
 $\Rightarrow \equiv_{\mathcal{D}}$  is **fully abstract** wrt.  $\equiv_{obs}$ :

$$\equiv_{obs} = \equiv_{\mathcal{D}}$$

# Object calculus: informal

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- formal model(s) of oo languages
- in the tradition of the  $\lambda$ -calculi, process calculi . . .
- more specifically:
  - object-calculi of Abadi/Cardelli [1]
  - $\pi$ -calculus: processes, parallelism, name-passing [11][14]
  - $\nu$ -calculus:  $\lambda$ -calc. with name creation (references) respectively its concurrent version [12][8]

# Concurrent $\nu$ -calculus with classes

- program = “set” of **named threads**, **objects**, and **classes**:  $n\langle t \rangle$ ,  $n[c]$  and  $n[l_1 = m_1, \dots, l_k = m_k]$
- dynamic **scoping** of names
  - $\nu n:T. (C_1 \parallel C_2)$
  - communication of names changes the scope (“**scope extrusion**”)
- **class** = “like” an object that accepts only a *new*-method; class names are not first-class citizens
- **methods** = functions with specific “**self**”-parameter *a*
- **active** entities: **threads**
  - sequencing + local, static scoping:  $let\ x = e\ in\ t$
  - thread creation

# Concurrent $\nu$ -calculus with classes

$C$	$::=$	$\mathbf{0} \mid C \parallel C \mid \nu(n:T).C \mid n[(n)] \mid n[O] \mid n\langle t \rangle$	program
$O$	$::=$	$l = m, \dots, l = m$	object
$m$	$::=$	$\varsigma(n:T).\lambda(x:T, \dots, x:T).t$	method
$t$	$::=$	$v \mid stop \mid let\ x:T = e\ in\ t$	thread
$e$	$::=$	$t \mid \text{if } v = v \text{ then } e \text{ else } e$	expr.
		$\mid v.l(v, \dots, v) \mid n.l \Leftarrow m \mid currentthread$	
		$\mid new\ n \mid new\langle t \rangle$	
$v$	$::=$	$x \mid n$	values



- given in various “stages”
  - **internal** (configuration-local) steps
  - **external**, global steps, interacting with the environment
  - computation steps **modulo  $\alpha$ -conversion**
- **typed** operational semantics

# ***F-A in an object-based conc. setting***

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- [9]: for the concurrent  $\nu$ -calculus
  - notion of **observation**: **may-testing** equivalence.  
Formalized here: whether a specific context method (*“o.success()”*) is called
  - **component** = set of parallelly “running” objects + threads
  - **observable**: message exchange at the **boundary**
- ⇒ fully abstract observable behavior = **communication traces** of the **labels** of the OS

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actually: they use may-**preorder**.

# What changes?

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- **classes** are units of exchange:  $\mathcal{C}[\mathbf{n}[(\mathbf{O})]]!$
- i.e., internal and external classes
- component objects can **instantiate external classes**

can one use these objects for “**observations**”?

- instances of external classes,
  - instantiation itself is **unobservable**
  - comm. between component and object **observable**
  - but:
    - their **existence** is (principally) unknown to the rest of environment ( $\neq$  OC),
    - **unless** the component gives away their identity!

# Completeness: line of argument

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- goal: if  $C_1 \equiv_{obs} C_2$ , then  $C_1 \equiv_{\mathcal{D}} C_2$
- so, given a legal trace  $s \in \llbracket C_1 \rrbracket_{\mathcal{D}}$ , do
  - **construct** a **complementary** context  $\mathcal{C}_{\bar{s}}$
  - **composition**: program + context do the observation

$$\mathcal{C}_{\bar{s}}[C_1] \longrightarrow^* success$$

- observational equivalence:  $C_2$  can do that, too:

$$\mathcal{C}_{\bar{s}}[C_2] \longrightarrow^* success$$

- **decomposition**:  $s \in \llbracket C_2 \rrbracket_{\mathcal{D}}$

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That  $s$  is a trace of  $C_2$  by decomposition is not a direct consequence. I

ignore that here

- **core** of completeness: **definability**  $\Rightarrow$
- for each **legal** trace  $s$ : construct a component  $C_s$  realizing it
- first: **characterize** the legal traces exactly
- derivability of **legal-trace**-judgement:

$$\Delta; E_\Delta \vdash r \triangleright \mathbf{s} : trace \Theta; E_\Theta$$

# Legal traces: incoming call

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- General setup: **scan** the trace, where
  - $r$ : **history**
  - $as$  **future** with **next label**  $a$

$$\frac{\text{lots of conditions} \quad \Delta'; \acute{E}_{\Delta} \vdash \quad \mathbf{r} \mathbf{a} \triangleright \mathbf{s} : trace \acute{\Theta}; \acute{E}_{\Theta}}{\Delta; E_{\Delta} \vdash \quad \mathbf{r} \triangleright \mathbf{a} \mathbf{s} : trace \Theta; E_{\Theta}}$$

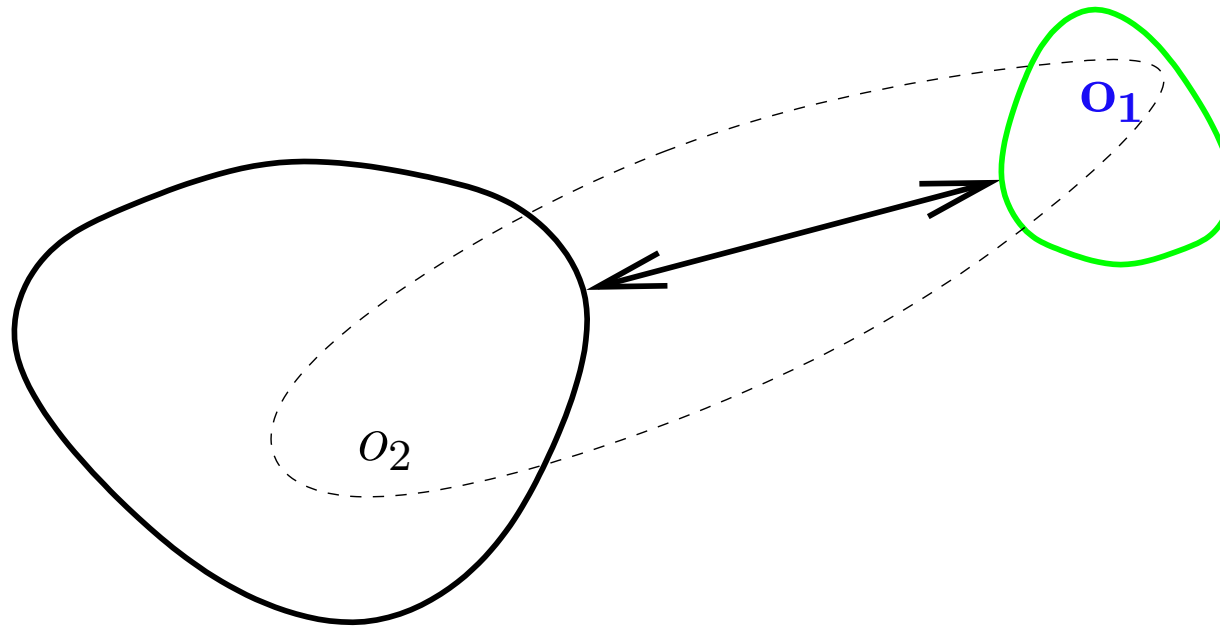
# ***“Lots of conditions”***

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- For **completeness**: component must realize all **possible** traces **but not more!**
- various aspects
  - “global”: call-return discipline = **balanced**/“**parenthetic**” (per thread)
  - “local”
    - no **name clashes**: scoping/**renaming**
    - well-typedness
    - **impossible name communication** (“connectivity”)

# Impossible incoming names?

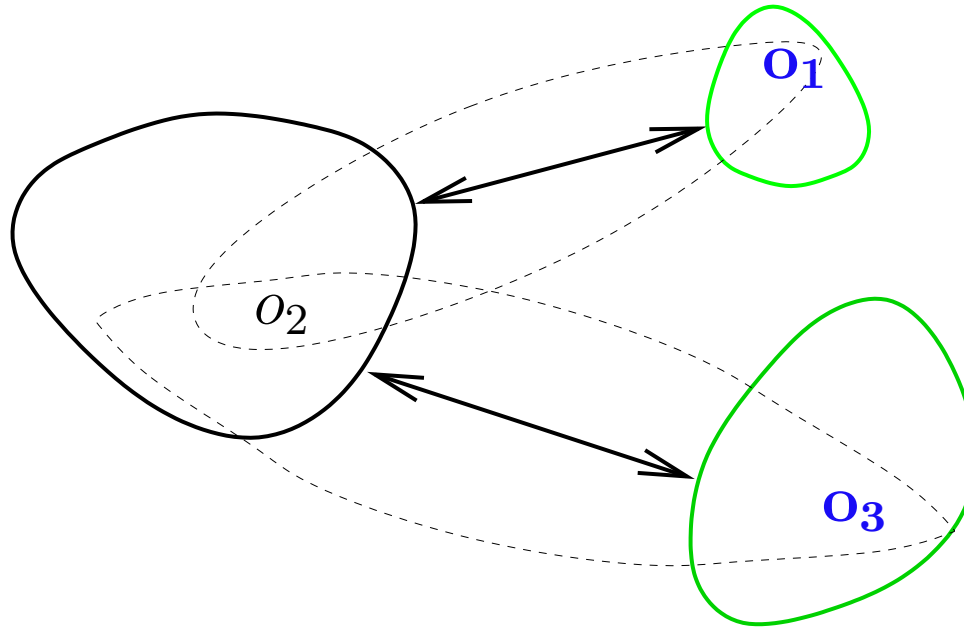
- Assume: component instantiates two external classes (into  $o_1$  and  $o_3$ )



- can  $o_1$  and  $o_3$  be sent in the same argument list? (for example)



# Impossible incoming names?



- trace labelled

$\nu o_1. \text{creates } \mathbf{o}_1!. \nu o_3. \text{creates } \mathbf{o}_3!. n' \langle [o'] \text{ call } o_2.l(\mathbf{o}_1, \mathbf{o}_3) \rangle?$

impossible!

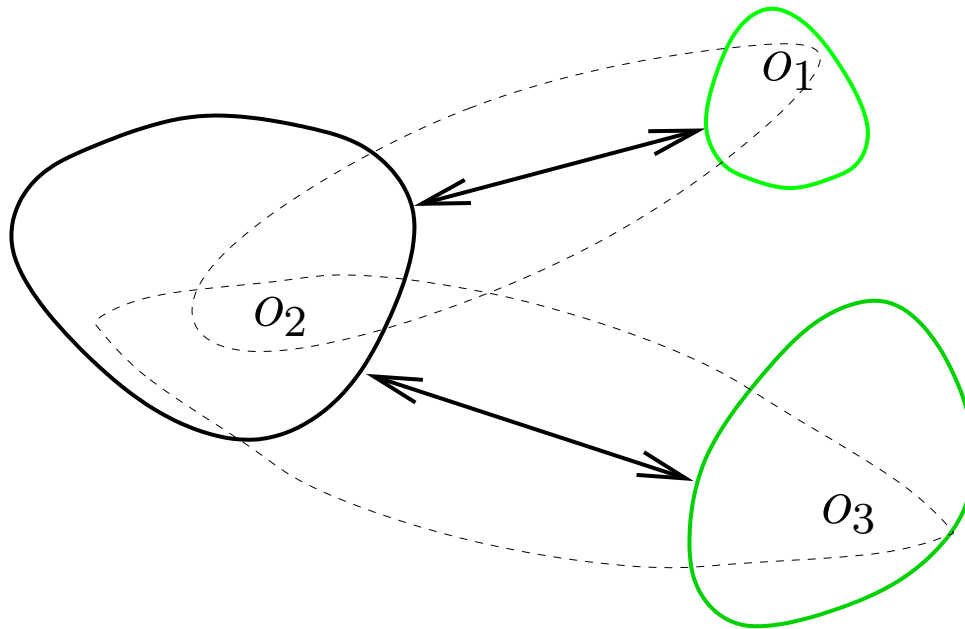
- $o_1$  and  $o_3$ : cannot occur in the same label and because

they do not possibly “know” of each other

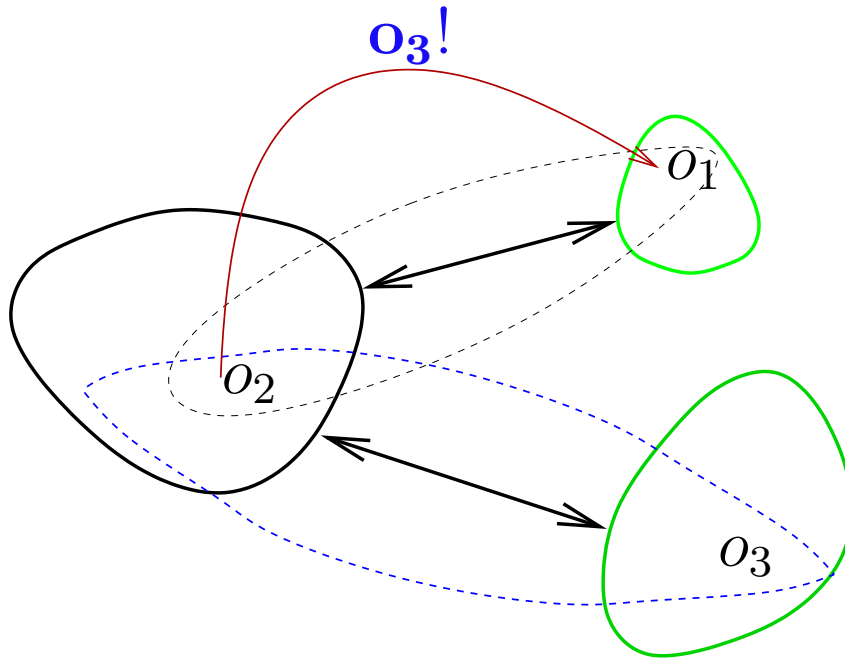
- if “connected”, they could occur in the same label
- connectivity or “acquaintance” is dynamic
- the only one to make  $o_2$  and  $o_3$  acquainted: the component

# Dynamic acquaintance

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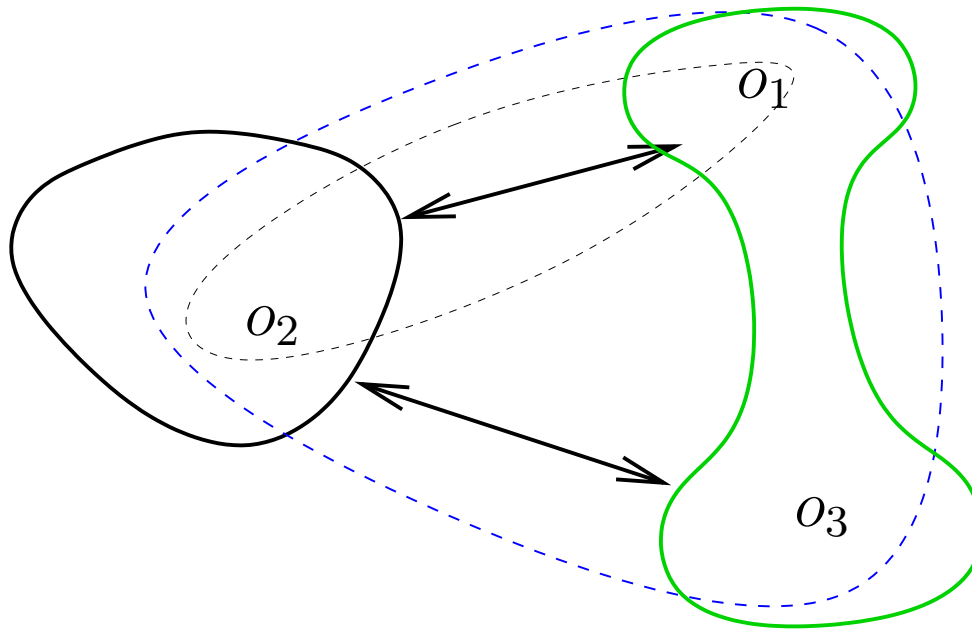
# Dynamic acquaintance



$$\Delta \vdash n\langle o_1.l(o_3); t \rangle \parallel o_2[\dots] : \Theta, o_2:T_2 \xrightarrow{n\langle [o_2] \text{ call } o_1.l(o_3) \rangle!} \Delta \vdash n\langle \text{block}; t \rangle \parallel o_2[\dots] : \Theta, o_2:T_2$$

- **no** scope extrusion from perspective of the component

# Dynamic acquaintance



- scope enlarged
  - $o_1$  knows  $o_3$
- $\Rightarrow$   $o_3$  **could know** now  $o_1$ , too
- and all objects that  $o_3$  knows, could know  $o_1$  in turn, too

...

# *Acquaintance: assumptions and commitments*

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- **acquaintance** = equivalence relation on object id's
- ⇒ **keep track** of (the worst-case) of connectivity
- ⇒ set of “equations”; **clique**: **implied equational theory**
- e.g., sending  $o_1$  to  $o_2$ , **adds**  $o_1 \hookrightarrow o_2$  to the equations

# Incoming call: acquaintance

- let  $a = n\langle[o_1] \text{ call } o_2.l(\vec{v})\rangle?$

$$\acute{E}_\Theta = E_\Theta + (\mathbf{o}_2 \hookrightarrow \vec{v})$$

$$\frac{E_\Delta \vdash \mathbf{o}_1 \rightleftharpoons; \hookrightarrow \vec{v} \quad E_\Delta \vdash \mathbf{o}_1 \rightleftharpoons; \hookrightarrow \mathbf{o}_2 \quad \Delta; \acute{E}_\Delta \vdash r \ a \triangleright s : \text{trace } \Theta; \acute{\mathbf{E}}_\Theta}{\Delta; E_\Delta \vdash r \triangleright a \ s : \text{trace } \Theta; E_\Theta}$$

# Incoming bound value

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- bound input:  $E_\Delta$  extended to  $\acute{E}_\Delta$
- crucial question

What is the connectivity of the new objects?

- we have to **guess**!

$\Rightarrow$  extend  $E_\Delta$  to  $\acute{E}_\Delta$ :



# Incoming bound value: arbitrary guess?

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- can the extension from  $E_\Delta$  to  $E'_\Delta$  be arbitrary?
- No:

“No news about old objects”

- i.e.,

“theory of  $E'_\Delta$ : a **conservative** extension of  $E_\Delta$ ”

- written:  $\mathbf{E}_\Delta \vdash \mathbf{E}'_\Delta \downarrow_{\Delta \times (\Delta + \Theta)}$

# Incoming call: bound input

- **let**  $a = \nu(\Delta'). n\langle[o_1] \text{ call } o_2.l(\vec{v})\rangle?$

$$\begin{array}{c} \dot{E}_\Theta = E_\Theta + (o_2 \hookrightarrow \vec{v}) \quad \dot{E}_\Delta \vdash o_1 \rightleftharpoons; \hookrightarrow \vec{v} \quad \dot{E}_\Delta \vdash o_1 \rightleftharpoons; \hookrightarrow o_2 \\ (\dot{\Delta}, \dot{E}_\Delta) = (\Delta, E_\Delta) + \Delta' \quad E_\Delta \vdash \dot{E}_\Delta \downarrow_{\Delta \times (\Delta + \Theta)} \quad \dot{\Delta}; \dot{E}_\Delta \vdash r \triangleright a \triangleright s : \text{trace } \dot{\Theta}; \dot{E}_\Theta \\ \hline \Delta; E_\Delta \vdash r \triangleright a \triangleright s : \text{trace } \Theta; E_\Theta \end{array}$$

- **extend** the assumption contexts
- check for conservativity of the **guess**

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One has also to extend the commitments; I omit this here.

# Legal traces: balance

- incoming call
- check for **input enabledness** per thread
- consult the **history**
- for instance: incoming return  $a$  possible in a next step

$$\frac{pop\ n\ r = \nu(\Theta').\ n\langle[o_1]call\ o_2.l(\vec{v})\rangle!}{\Delta \vdash r \triangleright \nu(\Delta').\ n\langle return(v)\rangle? : \Theta}$$

- before a return: there must have been an **outgoing call**
- *pop* picks out the last “**matching**” call

# Incoming comm.: the full story

$$\begin{array}{c}
 a = \nu(\Delta', \Theta'). n\langle[o_1] \text{ call } o_2.l(\vec{v})\rangle? \quad \dot{E}_\Theta = E_\Theta + (o_2 \hookrightarrow \vec{v}, n \hookrightarrow o_2) \\
 (\dot{\Delta}, \dot{E}_\Delta) = (\Delta, E_\Delta) + \Delta' \quad \Delta; E_\Delta \vdash \dot{E}_\Delta \downarrow_{\Delta \times (\Delta + \Theta)}: \Theta \quad \dot{\Theta} = \Theta + \Theta' \\
 ; \Theta \vdash o_2 : c_2 \quad ; \Theta \vdash c_2 : [\dots, l:\vec{T} \rightarrow T, \dots] \quad [\dot{\Delta}] \vdash [o_1 : [\dots]] \quad \dot{\Delta}, \Theta \vdash n: \text{thread} \quad ; \dot{\Delta}, \dot{\Theta} \vdash \vec{v} : \vec{T} \\
 \text{dom}(\Delta', \Theta') \subseteq \text{fn}(n\langle[o_1] \text{ call } o_2.l(\vec{v})\rangle) \\
 \dot{\Delta}; \dot{E}_\Delta \vdash [o_1] \rightleftharpoons \vec{v} : \dot{\Theta} \quad \dot{\Delta}; \dot{E}_\Delta \vdash [o_1] \rightleftharpoons o_2 : \dot{\Theta} \quad \dot{\Delta}; \dot{E}_\Delta \vdash n \rightleftharpoons [o_1] : \dot{\Theta} \\
 \Delta \vdash r \triangleright a : \Theta \quad \dot{\Delta}; \dot{E}_\Delta \setminus n \vdash r a \triangleright s : \text{trace } \dot{\Theta}; \dot{E}_\Theta \\
 \hline
 \Delta; E_\Delta \vdash r \triangleright a s : \text{trace } \Theta; E_\Theta
 \end{array}$$

- given a legal trace  $s \Rightarrow$  define  $C_s$  by

$\text{induction on the derivation for}$   
 $\Delta; E_\Delta \vdash r \triangleright s : \text{trace } \Theta; E_\Theta$

$\Rightarrow$  **construct** the program **backwards!**

actions on the commitment context  $E_\Theta$ :

$E_\Theta$ : each object knows its **clique**, kept up-to date

- giving away new id's: **create** them  
**propagate/broadcast** information through the clique
- incoming calls: **wrap up** the method body, put it into the class

- for example **outgoing call**  $a = \nu(\Theta'). n\langle [o_1] \text{ call } o_2.l(\vec{v}) \rangle!$
- we know: **afterwards**

$$\dot{C}_s = n\langle \text{let } x:T = [o_1] \text{ blocks for } o_2 \text{ in } t' \rangle \parallel C'_s$$

- construct component  $\dot{C}_s$  **before** the call:

$$C_s = C'_s \parallel n\langle \text{create}(\Theta'); \text{propagate}(\Theta'); \text{wait}(o_2, \vec{v}); o_2.\text{delegate}_l(o_1, \vec{v}); t \rangle$$

where  $t = \text{let } x:T = [o_1] \text{ blocks for } o_2 \text{ in } t'$ .

## *What I didn't mention*

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- static typing
- treatment of “cross-border” instantiation:
  - instantiation itself is not visible
  - “lazy instantiation”
  - guessing connectivity also for instances the “other side” instantiated in the component (and vice versa)
- caller identity must ultimately be ignored
- coding issues
- objects not acquainted cannot determine relative order of events of each other

- are classes good composition units?
- what about **cloning**?
  - cloning means: obtaining an identical **copy** (up-to the object identity) of an object “**on the run**”
  - **tree** semantics
  - **bisimulation** equivalence instead of traces
- **lock-synchronization**
- subtype **polymorphism** & **subclassing**
- technology transfer to the **proof systems**, compositionality



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