

# The Abstract Behavioral Specification Language (ABS)

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## **HATS: Highly Adaptable and Trustworthy Software using Formal Models**

## Main Ingredients

- ① **Executable**, formal modeling language for adaptable software: Abstract Behavioral Specification (ABS) language
- ② **Tool suite** for ABS/executable code analysis & development:
  - “Hard” feature consistency, security, property verification, code generation, type safety. . .
  - “Soft” simulation, visualization, test case generation, specification mining, . . .

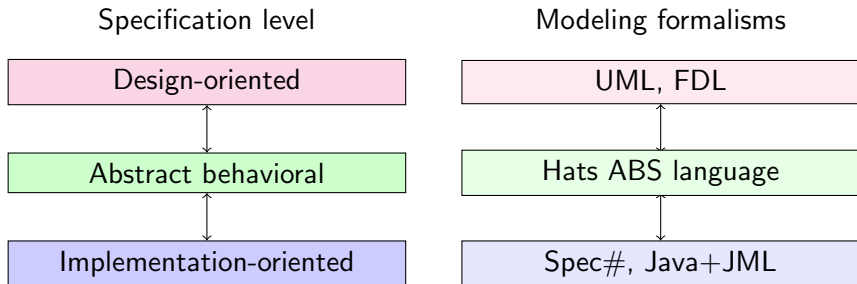
Develop analyses **in tandem** with ABS to ensure feasibility
- ③ Methodological and technological **framework** integrating HATS tool architecture and ABS language

## High adaptability combined with high trustworthiness

### Challenges

- Concurrency
- Distributedness
- Invasive composition
- different deployment scenarios
- Rapidly changing requirements
- Unanticipated requirements
- Trustworthiness (correctness, security, reliability, efficiency)

## Specification gap for large systems



## ABS is designed with analysability and verifiability in mind

- Expressivity, richness, etc., represent trade-offs
- More practical than “pure” formalisms such as  $\pi$ -calculus, Petri-nets
- State-of-art programming language concepts
- Modeling of realistic software
- Easier to specify/analyse than implementation-level languages
- Various abstraction mechanisms:
  - modularize (separate concerns, encapsulate)
  - permit incremental algorithms
- Modeling of variability a first-class concept

## Core ABS

- **Formal** semantics
- **Layered** architecture: simplicity, separation of concerns
- **Executability**: rapid prototyping, visualization
- **Abstraction**: underspecification, non-determinism
- Realistic, yet language-independent **concurrency model**
- **Component object groups** structure **composition** of concurrent objects
- **Assertion language**: first-order contracts for methods, classes

## Full ABS

- Syntactic **module** system
- **Feature modeling language**
- **Behavioural interface specifications**

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## Abstractions coming with the Creol subset

- Communication environment: unordered asynchronous messages
- Release points: underspecified scheduling of internal activities
- Interfaces as types: implementation independent, modularity
- ADTs: avoid representation objects and related reasoning problems

## Abstractions coming with Concurrent Object Groups

- Concurrency: lifts Creol's concept of cooperative scheduling to **groups** of objects
- At most one activity inside the **group**, all other activities are suspended

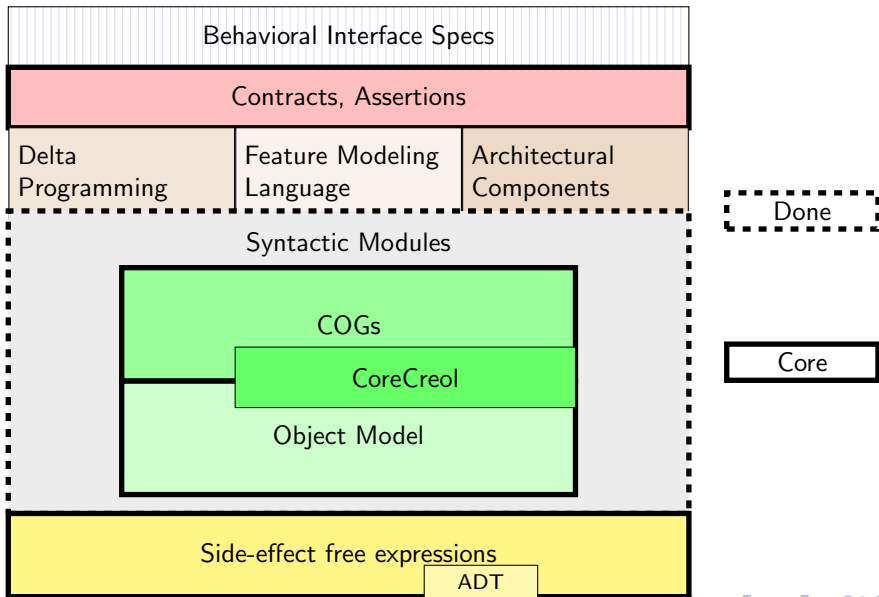
## What Core ABS does

- Addresses distributed and concurrent software
- Features user defined ADTs to abstract from repr. objects
- Synchronization in Core ABS is user-decided
- Executable
- Prototype tool chain and Maude interpreter finished
- Rudimentary contract-based assertion language

## What Core ABS does not

- Support SPL development, variability, features and feature integration
- Provide structuring concepts beyond interfaces, classes, and methods
- Modules, arch. components, superclasses, traits, deltas, ...
- Behavioral interface specifications

# Layered ABS Language Design



# Abstract Datatypes

```
data Bool = True | False; // built-in
data Unit = Unit; // built-in
data IntList = Nil | Cons(Int, IntList);
data List<A> = Nil | Cons(A, List<A>); // Parametric type
type IntList = List<Int>; // type synonym
```

# Functional Sublanguage

```
def Int length(IntList list) = //  
  case list { // definition by case distinction and matching  
    Nil          => 0 ;  
    Cons(n, ls) => 1 + length(ls) ;  
    -           => 0 ; // anonymous variable matches anything  
  } ;
```

```
def A head<A>(List<A> list) = // parametric function  
  case list {  
    Cons(x, xs) => x;  
  } ;
```

```
def A fromJust<A>(Maybe<A> a) =  
  case a {  
    Just(x) => x; // unbound variable used to extract value  
  } ;
```

# Interfaces and classes

- No class/code inheritance
- Implementation of multiple interfaces ok
- Sub-interfaces ok

```
interface Bar extends Baz { // Baz must be interface
    Method1;
    Method2;
    ...
}
```

```
class Foo(T x, U y) implements Bar, Baz { // = constructor
    T f = expr ; U g ; // fields with optional initialization
    { Initblock } // optional initialization block
    Method1 // method declarations
    Method2
    ...
}
```

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# Active Classes

- Objects from **active classes** start activity upon creation
- Characterized by presence of `run()` method
- Passive classes react only to incoming calls

```
Unit run() {  
    // active behavior ...  
}
```



# Methods

```
File getFile(String f, DataBase d) {  
    // Method Body (block)  
}
```

## Annotations

Methods (and classes, interfaces) can carry **annotations**:  
contracts, invariants, ...

# Blocks, Statements

## Blocks

- Sequence of variable declarations and statements
- Data type variables must be initialized
- Reference type variables are `null` by default
- Statements in block are **scope** for declared variables

## Statements

- Variable declarations
- Assignments
- `while–do`, `if–then–else`
- `await`, `suspend`
- (Method calls are expressions and appear e.g. in right sides of assignments)

## Synchronous Method Calls

- Syntax: `caller .m(e)`
- JAVA-like syntax and semantics
- Execution of caller method blocks
- Synchronisation is explicit decision of designer

## Asynchronous Method Calls

- Syntax: `caller !m(e)`
- Execution of caller method continues
- futures
- Variables that contain not yet available values have `future type`
  - `Fut<T> v; ...; v = o!m(e);`

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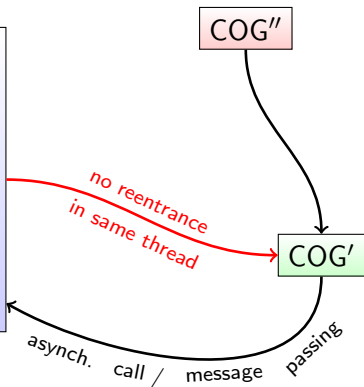
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- **futures**
- Variables that contain not yet available values have **future type**
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# Component Object Groups (COGs)

## COG

- One activity at a time
- Cooperative scheduling
- One lock
- Synchronous calls
- Callbacks (recursion) ok
- Shared access to data



# Scheduling and Synchronisation

## Yielding execution

- `suspend` command yields lock to other task in COG
- Unconditional scheduling point

## Synchronization of concurrent activities

- Wait until result of an asynchronous computation is ready
  - `await g`, where `g` is a monotonically behaving polling `guard` expression over `v?` and `v` is a future reference
- Retrieve result of asynchronous computation and copy into a future
  - `v.get`, where `v` is a future referring to a finished task
- Programming idiom:  
`Fut<T> v;...; v = o!m(e);...; await v?; r = v.get;`
- Conditional scheduling point

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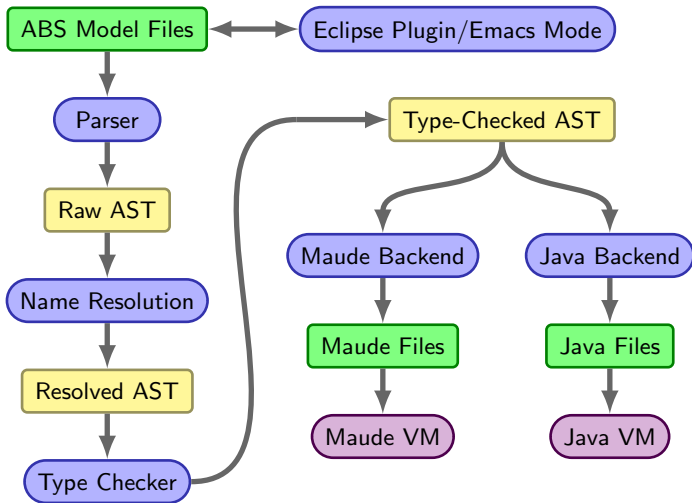
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# HATS Basic Tool Chain



## LEGEND

external data

internal data

ABS tool

existing tool



# Layered ABS Language Design

