Design issues in concurrent object-oriented languages and observability

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What are we dealing with?

Effect of facets of object-oriented languages on the observable behavior of open programs

- Classes: units of code
- Inheritance: code re-use
- Concurrency: multi-threading and active objects
- Synchronization: locks and monitors

Why important?

- verification
- black-box testing
- compositionality, replacement, full abstraction

- \implies Easy question, difficult answer
- \implies Open semantics.

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```
public class C { // component
    public static void main(String[] arg) {
        O x = new O();
        x.m(42); // call to the instance of O
    }
}
class O { // external observer
    public void m(int x) {
        ...
        System.out.println("success");
    }
}
```

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Open systems





• Component and its environment communicate via *method calls*.

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Characterizing the open semantics

 "message passing"¹ framework ⇒ the corresponding open semantics is "traces" as interface interactions (method calls and returns)

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¹no direct access to instance variables

Characterizing the open semantics

- "message passing"¹ framework ⇒ the corresponding open semantics is "traces" as interface interactions (method calls and returns)
- open = environment absent/arbitrary



¹no direct access to instance variables

Characterizing the open semantics

• operational description: assumption/commitment formulation

$$Ass. \vdash C: Comm. \xrightarrow{a} Ass. \vdash C: Comm.$$
(1)

• formal system to characterize interface behavior

$$\Delta \vdash C : \Theta \xrightarrow{a} \acute{\Delta} \vdash \acute{C} : \acute{\Theta} , \qquad (2)$$

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• interaction labels:

$$\begin{array}{lll} \gamma & ::= & p\langle call \ o.l(\vec{v}) \rangle \mid p\langle return(v) \rangle \mid \nu(n;T)_o & \text{basic labels} \\ a & ::= & \gamma? \mid \gamma! & \text{receive/send lal} \end{array}$$

• abstracting away the component, too:

 $\Delta, \Theta \vdash r \vartriangleright t : trace$

• inductive derivation system for legal traces:

check context: $\Delta, \Theta \vdash a$ update context: $\dot{\Delta}, \dot{\Theta} = \Delta, \Theta + a$ $\dot{\Delta}, \dot{\Theta} \vdash r \ a \rhd \ t : trace$ other conditions

 $\Delta, \Theta \vdash r \triangleright a t : trace$

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what is the semantical import of classes?

- Interface separates observer and component classes
- \Rightarrow instantiation requests as interface interaction
- 2 class = generators of object (via new)²
- abstraction of the heap topology

²Classes in *Java* or C^{\sharp} serve also as kind of types, and furthermore for inheritance. We ignore that mostly here.

Cross-border instantiation & heap abstraction



Heap separation

• heap is separated in component and environment part:





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Cross-border inheritance



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Separation in component & environment class $+\ cross\mbox{-border}$ inheritance

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- self-calls observable.
- abstraction of the heap topology
- State of an object is split into two halves.

• shared (instance) state + concurrency \Rightarrow mutex

- sync. mechanism: monitors
- for instance in Java
- but: re-entrant monitors (recursion)

• Now:

The addition of monitors increase or decrease the discriminating power?

- intuitively: 2 plausible answers:
 - the observer sees less!
 - the observer sees more!

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Example

- 2 calls, competing for the same (component) lock
- data dependence
 - o' received by the first call (of n_1)
 - returned by second thread n_2 afterwards
 - note: o' is new



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• question: is that trace possible?

Example

- 2 calls, competing for the same (component) lock
- data dependence
 - o' received by the first call (of n_1)
 - returned by second thread n_2 afterwards
 - note: o' is **new**

$$\gamma_{c_1}? \gamma_{c_2}? \gamma'_{c_1}! \gamma_{r_2}! =$$

 $(\nu o':c)n_1(\text{call } o.l(o'))? n_2(\text{call } o.l())? n_1(\text{call } \tilde{o}.l())! n_2(\text{return}(o'))!$

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• question: is that trace possible?

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- question: is that trace possible?
- the answer is no!
- data: "n₁ before n₂"
- monitors:
 - the outgoing call of n_1 shows that n_1 must have the lock now
 - \Rightarrow *n*₂ cannot have it now: \Rightarrow

" n_2 before n_1 "

$$\gamma_{c_1}? \gamma_{c_2}? \gamma'_{c_1}! \gamma_{r_2}! =$$

 $(\nu o':c)n_1(\text{call } o.l(o'))? n_2(\text{call } o.l())? n_1(\text{call } \tilde{o}.l())! n_2(\text{return}(o'))!$

• question: *is that trace possible*?

$$\gamma_{c_1}? \qquad \gamma_{c_2}?$$

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<u>Note:</u> *non-atomic* lock-grabbing \Rightarrow **no order!**

$$\gamma_{c_1}? \gamma_{c_2}? \gamma'_{c_1}! \gamma_{r_2}! =$$

 $(\nu o':c)n_1(call o.l(o'))? n_2(call o.l())? n_1(call \tilde{o}.l())! n_2(return(o'))!$

• question: *is that trace possible?*

$$\begin{array}{ccc} \gamma_{c_1}? & \gamma_{c_2}? \\ & & \\ \gamma_{c_1} \\ \gamma_{c_1}'! \end{array}$$

(3)

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<u>Note:</u> there is no order between events of n_1 and n_2 !

Example

 $\gamma_{c_1}? \gamma_{c_2}? \gamma'_{c_1}! \gamma_{r_2}! =$

 $(\nu o':c)n_1(\text{call } o.l(o'))? n_2(\text{call } o.l())? n_1(\text{call } \tilde{o}.l())! n_2(\text{return}(o'))!$

• question: is that trace possible?



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<u>Note:</u>

• data dependence because of o'

active objects

 $\bullet\,$ aynchronous method calls \Rightarrow each method call = new thread

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- no re-entrance
- unit of "state" \Rightarrow unit of concurrency
- lock state not observable
- observable semantics much easier
- better compositionality

• Object-orientation and modularity.

- Concurrency.
- Synchronization.

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