Inheritance and Observability

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 Class-based object-oriented multi-threaded programming languages with inheritance

What's the observable behavior of open programs in the presence of inheritance?

- Why important?
 - verification
 - black-box testing
 - compositionality, replacement, full abstraction
- ⇒ Easy question, difficult answer
- → Open semantics

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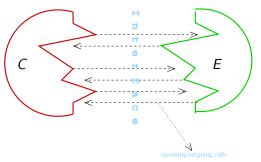
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```
public class C { // component
   public static void main(String[] arg) {
      O x = new O();
      x.m(42); // call to the instance of O
   }
}
```

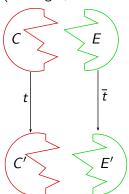
Open systems

- Component = set of objects + threads "running" in parallel
- Environment = "context" = "observer"

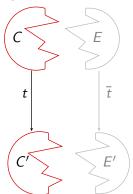


• Component and its environment communicate via asynchronous method calls.

⇒ Corresponding semantics is "traces" as interface interactions (messages, method calls and returns)



- "message passing" framework ⇒ in first approx.: semantics
 message interchange at the interface
- open = environment absent/arbitrary

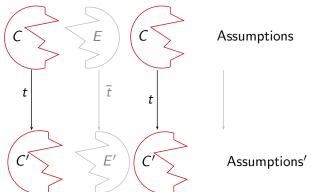


⇒ does this mean: environment behavior arbitrary/chaotic?



¹no direct access to instance variables

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- well, depends ...
- does "arbitrary trace" mean $\in Label^*$?
- we know $C \parallel E$ is a program of the language
 - well-formed
 - well-typed
 - class-structured with inheritance
- ultimately: proof of completeness is constructive
 - ⇒ formalization of "legal" traces
 - ⇒ constructive part: definability: given a trace, program a component that realizes "exactly" this trace.

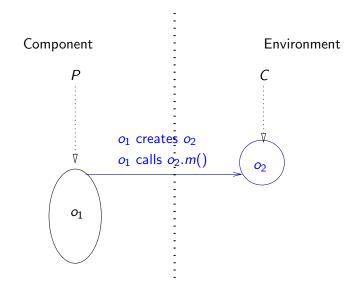
Open semantics

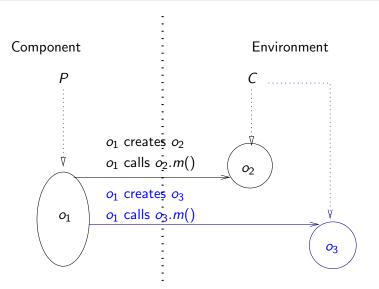
- operational description:
- assumption/commitment formulation
- Ass. \vdash C : Comm. \xrightarrow{a} Ass. \vdash Ć : Comm.
- interface: 2 orthogonal abstractions:
 - static abstraction: type system
 - dynamic abstraction of heap topology:

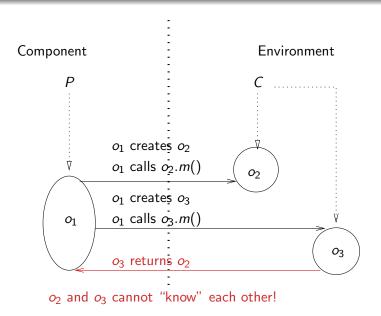
The influence of inheritance

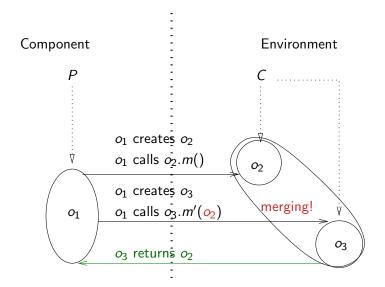
What is the semantical import of classes and inheritance?

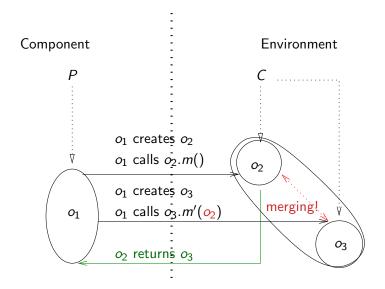
- Interface separates component and observer classes
- Classes are generators of object (via new)
- Component classes inherit from environment classes and vice versa.
- ⇒ instantiation and inheritance as interface interaction







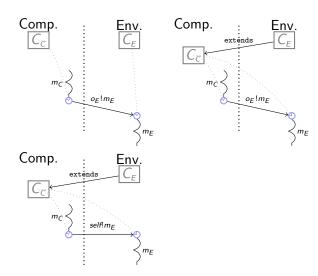




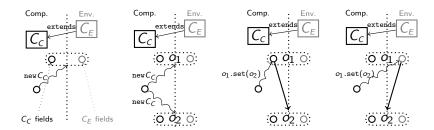
Observability of self-calls

- general intuition: "cross-border" interaction ⇒ interface-interaction
- self-calls: become observable
- cf. also [Viswanathan, 1998]

Cross-border inheritance



Cross-border inheritance and heap abstraction



Consequences of inheritance

- separation in component and environment class and cross-border inheritance
 - ⇒ self-calls observable.
 - ⇒ abstraction of the heap topology
 - ⇒ State of an object is split into two halves.

Formal framework: object calculus

- Types and classes:
 - statically typed, only well-typed components are considered
 - classes play role of types and generators of objects
 - single inheritance
- Concurrency: based on active objects/asynchronous method calls
- References:
 - objects and threads have unique names, i.e. identities
 - new objects dynamically allocated on the heap
- Fields are private

Grammar

```
:= \mathbf{0} \mid C \mid C \mid \nu(n:T).C \mid n[(O)] \mid n[O,L] \mid n(t)
                                                                                                            component
O ::= n, M, F
                                                                                                            obiect
M ::= l = m, \ldots, l = m
                                                                                                            method suite
F ::= I = f, \dots, I = f
                                                                                                            fields
m ::= \varsigma(n:T).\lambda(x:T,\ldots,x:T).t
                                                                                                            method
f ::= v \mid \perp_{n'}
                                                                                                            field
 t ::= v \mid \text{stop} \mid \text{let } x:T = e \text{ in } t
                                                                                                            thread
 e ::= t \mid \text{if } v = v \text{ then } e \text{ else } e \mid \text{if } undef(v.l()) \text{ then } e \text{ else } e
                                                                                                            expr.
              n@I(\vec{v}) \mid v.I() \mid v.I() := v
             new n \mid \text{claim}@(n, n) \mid \text{get}@n \mid \text{suspend}(n) \mid \text{grab}(n) \mid \text{release}(n)
v ::= x | n | ()
                                                                                                            values
 L ::= \bot | \top
                                                                                                             lock status
```

Open semantics and heap abstraction

- Exact interface behavior
- ⇒ Abstraction of the heap topology necessary
 - Keep track of "who has been told what":

$$\Delta$$
; $E_{\Delta} \vdash C : \Theta$; E_{Θ}

- Assumption context: $E_{\Delta} \subseteq \Delta \times \Delta = \text{pairs of objects}$
- Written $o_1 \hookrightarrow o_2$:
- Worst case: equational theory implied by E_{Δ}

$$o_1, o_2 \in \Delta : \quad E_{\Delta} \vdash o_1 \leftrightharpoons o_2$$

Operational semantics and heap abstraction

- as a labeled transition system
- Judgments of the form:

$$\Delta$$
; $E_{\Delta} \vdash C : \Theta$; E_{Θ} or short $\Xi \vdash C$

 Δ and Θ are name contexts E_{Δ} and E_{Θ} connectivity contexts

External steps

For interaction labels:

$$\begin{array}{lll} \gamma & ::= & p\langle \mathit{call} \ o.\mathit{l}(\vec{v})\rangle \mid p\langle \mathit{get}(v)\rangle \mid \nu(\mathit{n}:T)_o & \text{basic labels} \\ a & ::= & \gamma? \mid \gamma! & \text{receive and send labels} \end{array}$$

External steps: change of assumption/commitment contexts

- E.g., sending o_1 to o_2 , adds $o_2 \hookrightarrow o_1$ to the equations
- outgoing call
 - $a = n\langle call \ o_2.l(o_1)\rangle!$

$$\Delta; E_{\Delta} \vdash C : \Theta; E_{\Theta} \xrightarrow{a} \acute{\Delta}; \stackrel{\not{E}_{\Delta}}{\not{E}_{\Delta}} \vdash \acute{C} : \acute{\Theta}; \acute{E}_{\Theta}$$

- assumption update: $\not E_{\Delta} = E_{\Delta} + o_2 \hookrightarrow o_1$. We can have definition of assumption update here, similarly for name context check.
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Some of the external steps

$$a = p\langle call \ o.I(\vec{v})\rangle? \qquad \Xi \vdash a \qquad \acute{\Xi} = \Xi + a$$

$$\Xi \vdash C \parallel o[c, M, F, \bot] \xrightarrow{a} \acute{\Xi} \vdash C \parallel p\langle \text{let } x : T = M.I(o)(\vec{v}) \text{ in release}(o); x \rangle \parallel o[c, M, F, \bot]$$

Simplified rule for incoming call

$$a = n\langle call \ o_r.l(\vec{v})\rangle?$$

$$check \ context: \ \ \Xi \vdash a$$

$$update \ contexts: \ \ \dot{\Xi} = \Xi + a$$

$$semantic \ step \ (as \ in \ local \ semantics): \ from \ C \ to \ \dot{C}$$

Some of the external steps

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Simplified rule for incoming call

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update contexts: $\stackrel{\checkmark}{=} = \Xi + a$

semantic step (as in local semantics): from C to C

$$\Xi \vdash C \xrightarrow{a} \stackrel{\checkmark}{\Xi} \vdash \stackrel{\checkmark}{C}$$

putting it together: legal traces

- formal system to characterize interface behavior
- judgment:

$$\Xi \vdash a \ s : trace$$

• "after a and with assumption/commitment-contexts ≡, the trace s is possible"

putting it together: legal traces

Results

- formalization of open (representation-independent) semantics
 + characterization of possible (legal) interface behavior
- strict separation of assumptions and commitments
- subject reduction
- soundness of abstraction.

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