

A Calculus of Virtually Timed Ambients

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Motivation. The ambient calculus is the process algebra of locations and domains, originally developed by Cardelli and Gordon [2] for distributed systems such as the Internet. In this paper, we extend the ambient calculus with a notion of virtual time as a resource. The resulting calculus can be used for instance to model virtualization in cloud computing, where different locations, barriers between locations, and barrier crossing are important aspects, as well as elasticity which allows to provision virtual resources on-demand.

Previous work on timed process algebras. Algebraic concurrency theories such as ACP, CCS and CSP have been extended to deal with time-dependent behaviour in various ways (e.g., [1, 5, 3]). All these approaches describe speed as the absolute *duration* of processes, while in our approach speed describes the relative *processing power* of an ambient.

Preliminaries on mobile ambients. An ambient represents the location or domain where a process is running. Ambients can be nested, such that a surrounding *parental ambient* contains *subambients*, and the nesting structure can change dynamically. This is specified by three basic capabilities. The input capability *in* n indicates the willingness of a process, respectively its containing ambient, to enter an ambient named n , running in parallel outside, e.g., $k[in\ n.P] \mid n[Q] \rightarrow n[k[P] \mid Q]$. The output capability *out* n enables an ambient to leave its surrounding ambient n , e.g., $n[k[out\ n.P] \mid Q] \rightarrow k[P] \mid n[Q]$. The third basic capability *open* n allows to open an ambient named n which is on the same level as the capability, e.g., $k[open\ n.P \mid n[Q]] \rightarrow k[P \mid Q]$. This syntax, as well as the semantics we consider, is based on [4] and largely unchanged compared to [2].

Virtually timed mobile ambients. We extend mobile ambients with notions of virtual time and resource consumption. Virtual time is a resource, which is made available to a location by its parental location, similar to time slices that an operating system provisions to its processes. Interpreting the locations of ambients as a place of deployment, each timed ambient is modelled to have a certain computing power, determined by its deployment. Thus, our model of timed ambients uses a *local* notion of time, which, however, is *relative* to the computing power of the embedding, parental ambients.

Timed systems. A timed ambient contains one *local clock* and possibly other timed ambients or classic untimed ambients and processes. A *computing environment* is a timed ambient which contains *resources*, as explained below.

Local clocks. To represent the outlined time model, each timed ambient is equipped with one local clock responsible for triggering timed behaviour and local resource consumption. Clocks have a *speed*, interpreted *relative* to the speed of the surrounding timed ambient. The speed s of a clock is given by the rational number p/q , where p is the number of local time slices emitted for a number q of time slices received from the surrounding ambient. Time slices propagate from parental clocks to clocks in the subambients. Thus, the time in a nested ambient is relative to the global time, depending on the speeds of the clocks of the ambients it is nested in. We assume one universal outermost ambient with a *global clock* triggering the clocks of the local subambients recursively. When moving timed ambients, we must update the clocks to ensure a correct propagation of time slices, thus we use an *update function* and define timed capabilities **in** n , **out** n , and **open** n for timed systems, corresponding to the similar un-timed capabilities.

Computing resources. An ambient's processing power is defined by a *resource process* which transforms the time slices of the local clock into locally consumable resources. Processes expend the processing power of the ambient they are contained in by consuming resources. An ambient with a higher local clock speed produces more resources per parental time slice which in turn allows more work to be done for each parental time slice.

Weak bisimulation for timed ambients. We define weak timed bisimulation for virtually timed ambients as a conservative extension of weak bisimulation for mobile ambients as defined by Merro and Zappa Nardelli [4]. We then define a bisimulation for specific classes of processes which relaxes the condition on timing. This way we can determine how much faster one system is than another and give a worst case approximation for this timing difference. We finally show that weak timed bisimulation for ambients completely characterises reduction barbed congruence for virtually timed ambients, extending a result from [4].

References

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