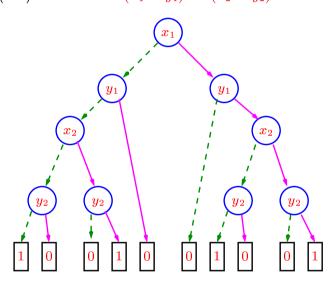
## BDD's

We start with a binary decision diagram. For example, following is a decision diagram (tree) for the formula  $(x_1=y_1) \land (x_2=y_2)$ :

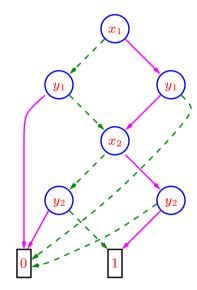


In general, it requires an exponential number of nodes.

## **Optimize**

- Identify identical subgraphs.
- Remove redundant tests.

## Yielding:



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#### **Definitions**

A binary decision diagram BDD is a rooted, directed acyclic graph with

- One or two nodes of out-degree zero labeled 0 or 1, and
- A set of variable nodes u of out-degree 2. The two outgoing edges are given by the functions low(u) and high(u). A variable var(u) is associated with each node.

A BDD is ordered (OBDD) if the variables respect a given linear order  $x_1 < x_2 < \cdots < x_n$  on all paths through the graph. An OBDD is reduced (ROBDD) if it satisfies:

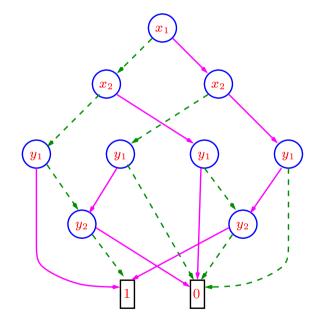
- Uniqueness no two distinct nodes are the roots of isomorphic subgraphs.
- No redundant tests  $low(u) \neq high(u)$  for all nodes u in the graph.

For simplicity, we will refer to ROBDD simply as BDDs.

## **Canonicity**

**Claim 4.** For every function  $f: Bool^n \to Bool$  and variable ordering  $x_1 < x_2 < \cdots < x_n$ , there exists exactly one BDD representing this function.

The complexity of BDD representation is very sensitive to the variable ordering. For example, the BDD representation of  $(x_1 = y_1) \land (x_2 = y_2)$ under the variable ordering  $x_1 < x_2 < y_1 < y_2$  is:



## Implementation of BDD Packages

### Types and Variables:

```
naturals
var\_num = naturals
                   record of
                        var
                                    : var\_num;
node\_rec =
                        low, high : node
                  end_record
                node \rightarrow node\_rec
                node\_rec \rightarrow node \cup \{\bot\}
```

#### **Operations:**

```
init(T)
                            Initialize oldsymbol{T} to contain only 0 and 1
u := new(T, i, \ell, h)
                            allocate a new node u, such that
                            T(u) = \langle i, \ell, h \rangle
init(H)
                            initialize H to \bot
```

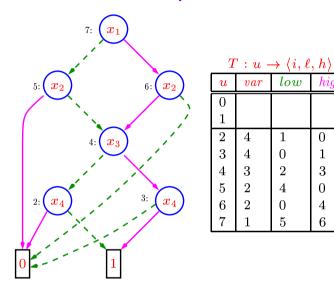
H is the inverse of T. That is, H(T(u)) = u, for every  $u \in dom(T)$ .

We will write var(u), low(u), high(u), and  $H(i, \ell, h)$  as abbreviations for T(u).var, T(u).low, T(u).high, and  $H(\langle i, \ell, h \rangle)$ .

## **Internal Representation**

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### Making or Retrieving a node\_id

```
Function \operatorname{MK}(i: \mathit{var\_num}; \ell, h: node) : node
--\operatorname{Make or retrieve a node with attributes}(i, \ell, h)
1: if \ell = h then return \ell
2: if H(i, \ell, h) \neq \bot then return H(i, \ell, h)
3: u := new(i, \ell, h)
4: H(i, \ell, h) := u
5: return u
```

# Applying a Binary Boolean Operation to two BDD's

Let  $op : \mathbf{Bool} \times \mathbf{Bool} \to \mathbf{Bool}$  be a binary boolean operation. The following function uses the auxiliary dynamic array  $G : node \times node \to node$ .

```
Function Apply (op; u_1, u_2 : node) : node
                                           - - Apply op to BDD's u_1 and u_2
  G := \bot
 function App(u_1, u_2 : node) : node =
    if G[u_1, u_2] \neq \bot then return G[u_1, u_2]
    if u_1 \in \{0,1\} \land u_2 \in \{0,1\} then u := op(u_1, u_2)
    else if var(u_1) = var(u_2) then
      u := MK(var(u_1), App(low(u_1), low(u_2)),
                         App(high(u_1), high(u_2)))
    else if var(u_1) < var(u_2) then
      u := MK(var(u_1), App(low(u_1), u_2), App(high(u_1), u_2))
    else (*var(u_1) > var(u_2)*)
      u := MK(var(u_2), App(u_1, low(u_2)), App(u_1, high(u_2)))
    G[u_1, u_2] := u
    return u
  end App
 return App(u_1, u_2)
```

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#### ----

```
Function REST (u:node;\ j:var\_num;\ b:Bool):node
-- \text{Substitute }b \text{ for } x_j \text{ in BDD }u
G:=\bot

function res(u:node):node=
if G[u]\neq\bot then return\ G[u]
if var(u)>j then r:=u
else if var(u)<j then
r:=\operatorname{MK}(var(u),res(low(u)),res(high(u)))
else (*var(u)=j*) if b=0 then r:=low(u)
else r:=high(u)
G[u]:=r
return r
end res
```

**Restriction (Substitution)** 

Restriction is the same as substitution. We denote by  $t[x \mapsto b]$  the result of substituting b for x in assertion t.

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## Quantification

Existential quantification can be computed, using the equivalence

$$\exists x: t \sim t[x \mapsto 0] \lor t[x \mapsto 1]$$

Universal quantification can be computed dually:

$$\forall x: t \sim t[x \mapsto 0] \wedge t[x \mapsto 1]$$

### **Application to Symbolic Model Checking**

Let V be the state variables for the FDS  $\mathcal{D}$ . Taking a vocabulary  $U=V\cup V'$ , we represent the state formulas  $\Theta$ , J for each  $J\in\mathcal{J}$ ,  $p_i$ ,  $q_i$ , for each  $\langle p_i,q_i\rangle\in\mathcal{C}$ , and the SMC-INV symbolic working variables new and old as BDD's over U which are independent of V'.

The transition relation  $\rho$  is represented as a BDD over U which may be fully dependent on both V and V'.

All the boolean operations used in the SMC-INV algorithm can be implemented by the Apply function. Negation can be computed by  $\neg t = t \oplus 1$ , where  $\oplus$  is sum modulo 2.

To check for equivalence such as old = new we compute  $t := (old \leftrightarrow new)$  and then verify that the result is the singleton BDD 1.

The existential pre-condition transformer is computed by

$$\rho \diamond \psi = \exists V' : \rho(V, V') \wedge \psi(V')$$

Priming an assertion  $\psi$  is performed by

$$prime(\psi) = \exists V : \psi(V) \land V' = V$$